PEAS:

P 🡪 speed , safe , time

E 🡪 air , customer , resturant , pizza

A 🡪 accelerator , broke

S 🡪 camera , GPS

ODESA:

O 🡪 partial

Stochastic D 🡪

E 🡪 sequential

S 🡪 dynamic

A 🡪 single agent

Goal-based agent

Because it's take action according to the current precept and the rest of percept history and comparing precepts with previous models to get the best result .